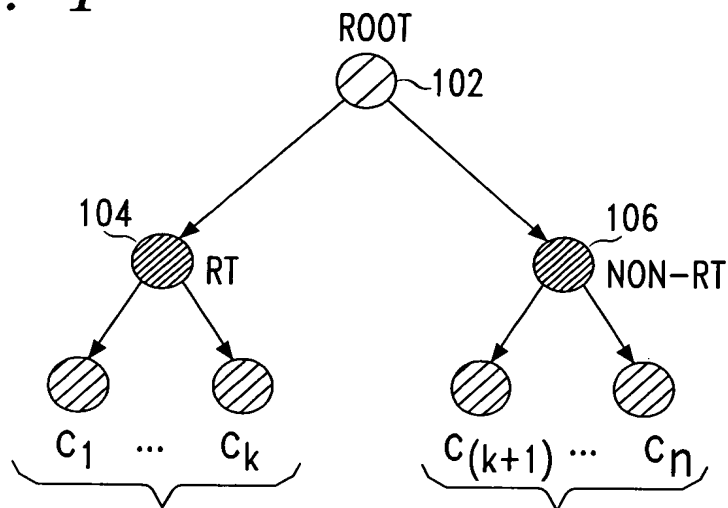


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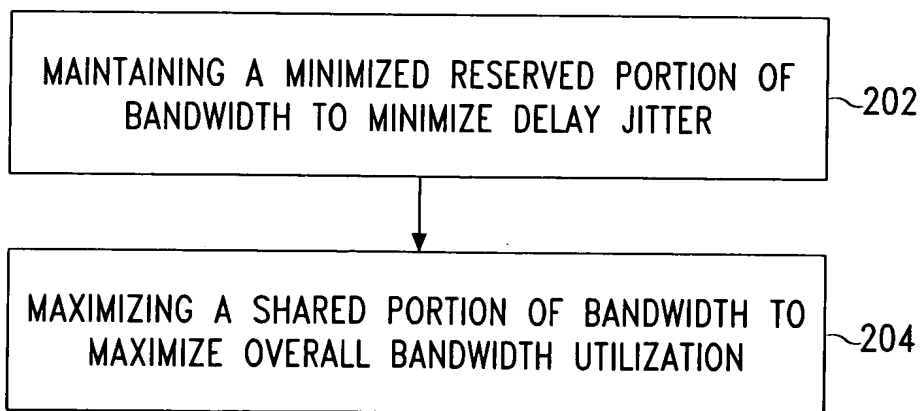
FIG. 1



WHERE BORROWING
PERMIT FOR $c_1 \dots c_k$
PERMITS TEMPORARY
BORROWING FROM RT
104 AND ROOT 102

WHERE BORROWING PERMIT
FOR $c_{(k+1)} \dots c_n$
PERMITS TEMPORARY
BORROWING FROM NON-RT
106 ONLY

FIG. 2



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FIG. 3

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COMPUTER-READABLE MEDIUM/METHOD

MEASURING A PREDETERMINED PARAMETER AT PREDETERMINED OBSERVATION WINDOW TIMES

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DYNAMICALLY ADJUSTING ALLOCATED BANDWIDTH FOR PARENT CLASSES OF REAL-TIME TRAFFIC BY ADJUSTING AN AVERAGE OF THE PREDETERMINED PARAMETER TO HAVE A VALUE WITHIN A PREDETERMINED STABLE REGION

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WHERE THE PREDETERMINED PARAMETER IS A NUMBER OF BORROWING ATTEMPTS DURING A MEASUREMENT WINDOW, A MAXIMUM BANDWIDTH AND A MINIMUM BANDWIDTH FOR THE PREDETERMINED STABLE REGION IS DETERMINED BY:

If $A_{i_avg} < Thr(A_i)^{lower}$, $B_i = maximum(B_i - \omega_i, Min(B_i))$

Else If $A_{i_avg} > Thr(A_i)^{upper}$, $B_i = minimum(B_i - \omega_i, Max(B_i))$

WHERE EXPONENTIAL SMOOTHING INCLUDES:

$A_{i_avg} \leftarrow (1-a) * A_{i_avg} + a * A_i$, WHERE A VALUE OF a IS PRESELECTED AS A NEGATIVE POWER OF TWO AND A_{i_avg} IS UPDATED EVERY OBSERVATION WINDOW, A PRE-DETERMINED PARAMETER IN SECONDS AND

THE QUEUE LENGTH Q_i FOR CLASS i MAY BE RELATED TO THE UPPER BOUND OF DELAY JITTER AS:

$$DELAY_JITTER_i = Q_i / B_i$$

SUCH THAT, WHERE THE DESIRED JITTER UPPER BOUND $Delay_jitter_i$ IS GIVEN, THEN A LINEAR RELATIONSHIP EXISTS BETWEEN Q_i AND B_i (ALLOCATED BANDWIDTH)

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WHERE THE PREDETERMINED PARAMETER IS A QUEUE LENGTH, A LOWER THRESHOLD AND AN UPPER THRESHOLD FOR QUEUE LENGTH FOR THE PREDETERMINED STABLE REGION MAY BE DETERMINED BY:

If $Q_{i_avg} < Thr(Q_i)^{lower}$, $B_i = maximum(B_i - \omega_i, Min(B_i))$

Else If $Q_{i_avg} > Thr(Q_i)^{upper}$, $B_i = minimum(B_i - \omega_i, Max(B_i))$

$Delay_jitter_i = max Q_i / B_i$

WHEREIN, IF A JITTER UPPER BOUND $Delay_jitter_i$ IS PRESELECTED, THEN A LINEAR RELATIONSHIP EXISTS BETWEEN $max Q_i$ AND B_i , AN ALLOCATED BANDWIDTH.

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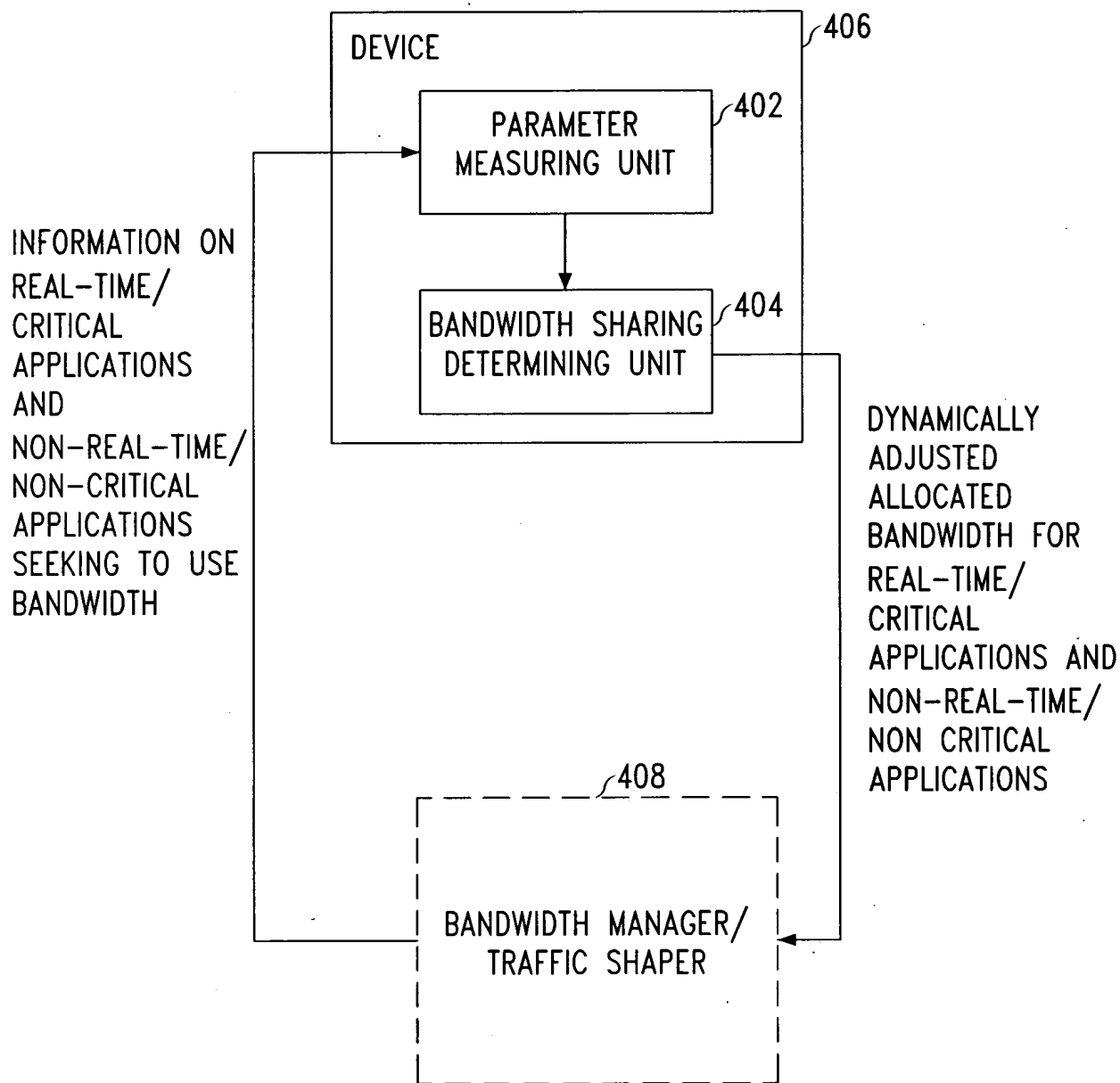


FIG. 4